

[0012] FIG. 3 is an exploded perspective view of a prior art registration system employing backlighting techniques;

[0013] FIG. 4 is a perspective view of a laser pattern generator system fabricated in accordance with one embodiment of the present invention;

[0014] FIG. 5 is a plan view showing, in detail, the optical components of the laser pattern generator shown above in FIG. 4;

[0015] FIG. 6 is a detailed plan view of a workpiece, having photo-sensitive material and mylar thereon, disposed on a platen, shown above in FIG. 4;

[0016] FIG. 7 is a magnified top-down view showing a fiducial, discussed above with respect to FIG. 5, illuminated employing top-down-dark-field illumination;

[0017] FIG. 8 is a magnified top-down view showing a fiducial, discussed above with respect to FIG. 5, illuminated employing top-down-bright-field illumination;

[0018] FIG. 9 is a detailed plan view of the workpiece, shown above in FIG. 6, employing backlighting in accordance with one embodiment of the present invention;

[0019] FIG. 10 is a detailed plan view of the workpiece, shown above in FIG. 9, having photo-sensitive material and mylar on both sides thereof;

[0020] FIG. 11 is a top-down view of the platen shown above in FIG. 4;

[0021] FIG. 12 is a cross-sectional view of a platen, shown above in FIG. 11, in accordance with one embodiment of the present invention;

[0022] FIG. 13 is a cross-sectional view of a platen shown above in FIG. 11, in accordance with a first alternate embodiment of the present invention;

[0023] FIG. 14 is a cross-sectional view of a platen shown above in FIG. 11, in accordance with a second alternate embodiment of the present invention; and

[0024] FIG. 15 is a flow diagram showing a method of determining alignment of a workpiece, with respect to a tool, in accordance with one embodiment of the present invention.

DESCRIPTION OF THE SPECIFIC EMBODIMENTS

[0025] Referring to FIG. 4 a perspective view of a laser pattern generator system 21 fabricated in accordance with one embodiment of the present invention is shown. System 21 is suitable for generating patterns on a photosensitive layer, referred to as a workpiece 22, employing a beam source, referred to as a tool 24. To that end, system 21 includes a frame 26 to which a stage 28 is coupled. A platen 25 is disposed on stage 28, and workpiece 22 lies upon platen 25. Stage 28 is moveably attached to frame 26 to reciprocate in three directions, x, y and z, and rotate about the z direction. To that end, a first servo-mechanism 30, in data communication with a processor 34, is coupled to stage 28 to facilitate movement along the x direction. A second servo-mechanism 36, in data communication with processor 34, is coupled to stage 28 to facilitate movement in the y direction. A third servo mechanism 38, in data communication with processor 34, is coupled to stage 28 to facilitate

movement in the z direction, as well as rotation about the z direction. Movement of stage 28 is achieved under control of processor 34. Platen 25 includes a plurality of vacuum grooves, one of which is shown as 27. Vacuum grooves 27 are in fluid communication with a vacuum system 29 and ensure that workpiece 22 is held flat against platen 25.

[0026] A boom 42 is coupled to frame 26 and extends parallel to the x direction. A laser 44 is in optical communication with tool 24. Under control of processor 34, laser 44 outputs a beam (not shown) that impinges upon workpiece 22 to form a pattern thereon. Movement between workpiece 22 and tool 24 is achieved by activating first and second servo-mechanisms 30 and 38 to translate stage 28 along the x and y directions, as discussed above. This allows the beam (not shown) to impinge upon any area of workpiece 24 as desired.

[0027] Referring to FIG. 5, laser 44 provides a radiant energy beam 46 for system 21 and is, for example, typically a five Watt, Argon-ion laser operating over a range of wavelengths of 351-385 nanometers. A pick-off mirror (not shown) directs beam 46 into a laser relay 48, causing beam 46 to impinge upon an automatic beam steering apparatus 50 (ABS). ABS apparatus 50 corrects for spatial drift in beam due, for example, to thermal fluctuations in laser 44, which ensures proper alignment of beam 46. This reduces the need to control the temperature of laser 44. This, in turn, reduces the need to perform manual alignment of beam 46. A multi-channel modulator 52 (MCM) is positioned after ABS 50. MCM 52 includes a beam splitter 54 and an Acousto-Optical Modulator 56 (AOM). Beam splitter 54 segments beam 46 into a plurality of beams, forming a beam brush 58. AOM 56 modulates the intensity of the beams associated with brush 58, as desired under control of a data path 60. To that end, data path 60 comprises a dedicated processor that operates on computer readable code to regulate the AOM operational parameters.

[0028] After exiting MCM 52, brush 58 passes through a scan lens system 62 that includes, for example, a rotating polygonal mirror 64, as well as pre-polygonal optics 66 and post-polygonal optics 68. Pre-polygonal optics 66 causes the beams of brush 58 to converge to a spot onto rotating polygonal mirror 64. Rotating polygon mirror 64 has a plurality of facets and causes brush 58 to scan workpiece 22 along a scan axis. One embodiment of the present invention employs a scan axis that extends parallel to the x direction and is approximately six inches in length. However, the scan axis may be of any length and any direction desired. For example, the scan axis may extend across the entire width of workpiece 22 along the x direction. In the present example, for a given pattern the rotating polygonal mirror rotates at a constant rate, but may be varied to match stage 28 velocity.

[0029] The beams reflected from polygonal mirror 64 then pass through post-polygonal optics 68 directing the same into relay 70. The beams exiting relay 70 scan workpiece 22. Specifically, to form an image on workpiece 22, workpiece 22 is scanned as stage 28 moves in the y direction, and the beam scans along the scan axis. This results in a plurality of scans, each of which is six inches in length. Each of the scans is displaced from an adjacent scan along the y direction. Thereafter, stage 28 moves in the x direction in preparation for another sequence of scans, each of which occurs in the scan axis, while stage 28 moves along y